BEST STUDENT PAPER AWARD – RUNNER UP

2018 IEEE International Conference on Simulation, Modeling, and
Programming for Autonomous Robots (SIMPAR) is presented to

**Ciro Potena, Bartolomeo Della Corte, Daniele Nardi, Giorgio Grisetti,
Alberto Pretto**

for the paper entitled

**Non-Linear Model Predictive Control with Adaptive
Time-Mesh Refinement**

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